

# From MisuseCase to Analysis Data

How to use a functional toolchain for expert based AI analysis Arlena Wellßow, OFFIS

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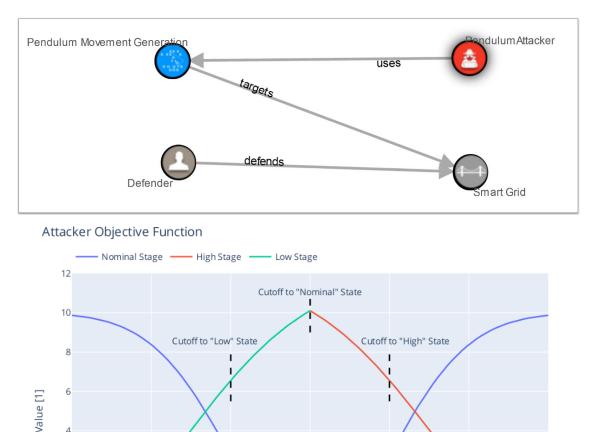
### **General Idea**



- Build a chain from expert knowledge to analyzed knowledge base
- 6 Steps:
  - 1. Structure Expert Knowledge
  - 2. Make Knowledge Machine Readable
  - 3. Generate an Experiment from Knowledge
  - 4. Use the arsenAl / palaestrAl Toolchain
  - 5. Analyse the Data
  - 6. Re-add the Data to the Knowledgebase

### Running Example

- So called "Pendulum Attack"
- Attacker uses the reaction of the defender for the attack
- Leads to an oscillating behavior



Voltage Magnitude [p.u.]

1.05

1.1

0.85

0.9

0.95

### **RES** *i*

1.15

## Step 1: Structure Expert Knowledge RES II

- Done by filling out "MisuseCase"-Templates (with additional parameters or in combination with additional techniques)
- Everything a domain expert knows about the attack is structured and documented
- This document can be shared with other experts to benefit from extensive domain knowledge exchange

### MisuseCase Template



#### Misuse Case Template

#### **Description of the Misuse Case** 1

#### Name of the Misuse Case 1.1

Misuse Case Identification				
ID	Area Domain(s)/ Zone(s)	Name of Misuse Case		
MUC_2		Generation of pendulum movement in the voltage band		

#### 1.2 Version Management

Version Management						
Version No.	Date	Name of Author(s)	Changes	Approval Status		
0.1	05.08.2022	Arlena <u>Wellßow</u>	First Draft	Draft		

#### Scope and Objectives of Misuse Case 1.3

Scope and Objectives of Misuse Case				
Scope				
Objective(s)				
Related Business Case(s)				

#### 1.4 Narrative of Misuse Case

Narrative of Misuse Case Short Description **Complete Description** 

#### Misuse Case Conditions **1.5**

Misuse Case Conditions			
Assumptions			
Prerequisites			

### **RES**Fli Step 2: Make Knowledge Machine Readable

- Export the Domain Knowledge Documents in machine readable formats like XML
  - Possible for e.g. Word, UML
- Read XML data in a programming language of choice
  - In our case: python

### **RES**Fli Step 3: Generate an Experiment from Knowledge

Use the machine readable domain knowledge to export every experiment relevant information

- E.g. objectives of the agents, name of the attack, KPIs, ...
- Analyse XML data and write the important information to a .yaml experiment file

%YAML 1.2

# The Classic ARL reference experiment

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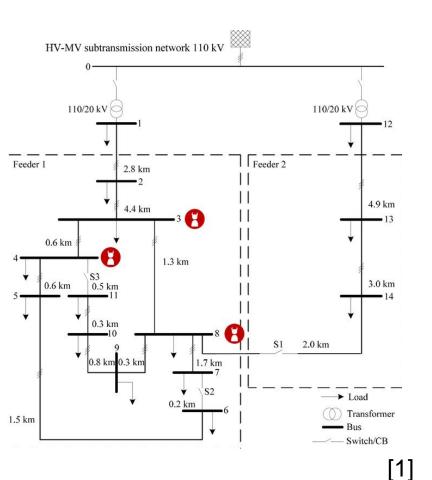
uid: Cost Based Experiment seed: 20222811 # Seed used to initialize the random number generator version: 3.4.1 # Target palaestrAI version output: palaestrai-runfiles # Directory where the run files will be saved repetitions: 1 # How often each run will be repeated. Each repetition is a separate file max\_runs: 10 # Maximum number of runs (excluding repetitions) created by the DoE generator definitions: # In this section all the components will be defined # The environment' section environments: midasmv\_tar\_ms: environment: name: palaestrai\_mosaik:MosaikEnvironment uid: midas\_powergrid params: module: midas.tools.palaestrai:Descriptor # Always the same if you use MIDAS description\_func: describe # Always the same if you use MIDAS instance\_func: get\_world # Always the same if you use MIDAS arl\_sync\_freq: &step\_size 900 # &step\_size 1 means to set variable step\_size=1 end: &end 9001 # One step extra because one step gets "lost" silence\_missing\_input\_connections\_warning: True params: # Parameters that are passed to description\_func and # instance\_func, Part that is being sent to MIDAS directly name: carl\_cigre\_ts config: midas-scenarios/classic-arl.yml end: \*end step\_size: \*step\_size # &step\_size put here from above with value 1 start\_date: 2020-05-01 00:00:00+0100 # Use ISO datestring or magic keywork 'random' mosaik\_params: {addr: [127.0.0.1, 56781]} store\_params: #everything in here overwrites what is written in classic-arl.yml in /midas-scenarios/ buffer\_size: 1000 # Every x steps, intermediate results are dumped to the midas store keep\_old\_files: true filename: retro\_psi\_midas.hdf5

#### reward:

name: midas.tools.palaestrai.rewards:RetroPsiReward

# The agents' section





#### **RES** is Step 4: Use the ArsenAI / PalaestrAI toolchain

- Read in YAML to arsenAl
- Then run palaestrAl



#### palaestrAI: General Toolchain

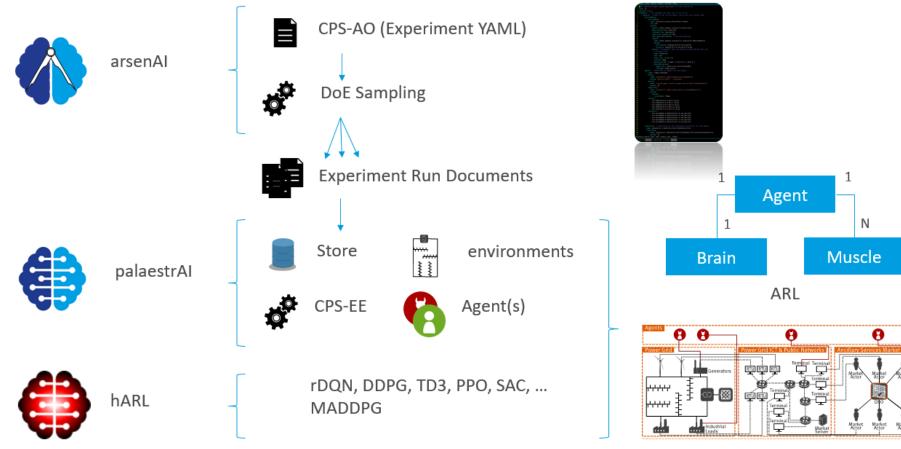


Image done by E. Veith in the project context

### arsenAl Experiment Definition



- arsenAl is the Experiment Design part of proper experimentation
  - Defines Parameters and Factors
  - Does a space-filling design sampling to construct concrete experiment runs
  - Nomenclature: Experiment => arsenAl (sampling) => Experiment Run
- All experiment runs are reproducible blueprints for actual runs
- Experiment and Experiment Run documents are stored in the database
- Experiments plug agents into environments (all are loadable modules)
- Format: YAML

```
# The agents' section
agents:
 Attacker:
   name: Attacker
   brain:
     name: harl.ppo.brain:PPOBrain
     params:
       max_timesteps_per_episode: 64
    muscle:
     name: harl.ppo.muscle:PPOMuscle
     params: {}
   objective:
     name: psi_objectives.voltage_attacker_objective:VoltageBandViolationPendulum
     params: { }
  Defender:
   name: Defender
   brain:
     name: harl.ppo.brain:PPOBrain
     params:
       max_timesteps_per_episode: 64
    muscle:
     name: harl.ppo.muscle:PPOMuscle
     params: {}
   objective:
     name: psi_objectives.voltage_defender_objective:VoltageDefenderObjective
     params:
       beta: 2
# The sensors' section
sensors:
  all_sensors:
   midas powergrid:
     - midas_powergrid.Powergrid-0.0-bus-1.vm_pu
     - midas_powergrid.Powergrid-0.0-bus-1.va_degree
     - midas_powergrid.Powergrid-0.0-bus-10.vm_pu
     - midas_powergrid.Powergrid-0.0-bus-10.va_degree
     - midas_powergrid.Powergrid-0.0-bus-11.vm_pu
```

#### RES\*Ii Anatomy of an Experiment Definition

- Experiment definition documents consist of
  - Definitions of agents, sensor/actuator lists, environments, and halting conditions (parameters)
  - Definition of experiment phases (factors)
- arsenAl run: Sampling
  - Chooses optimal space-filling design according to the number of factors and max samples desired
  - 1 Experiment definition can yield 100, 200, ... 1000, ... experiment runs
- palaestrAl executes experiment runs phase-by-phase
  - E.g., train agent, test agent (or any other combination of agents, sensor/actuator assignments, environments, halting conditions, etc you can think of)
  - palaestrAl re-loads states of agents from previous phases, if wanted

### Step 5: Analyze the Data



- Check generated data
- Evaluate the learned patterns of the attacking agent
- Future Work: Read out explainable moves from the agent for new strategies



[1]

### **RES**¥li**9**

### Step 6: Re-add the Data to the Knowledgebase

- At a later stage of the project
- Read in structured analysis data to e.g. STIX dataformat
- A TAXII-Server was already established and filled with already (in STIXformat) existing data

### First Breakthrough [1]



- First five steps were absolved by a prototyped workflow
- A already known attack was taken and written to the structured MUC-template
- First information was read into an experiment file
- General data was analysed to check the behaviour of the attacking agent

#### •

• And of course: Train a defending agent to handle the attacks

#### Lookout

- Projectscope:
  - Trajectories
  - Re-add data to a Knowledgebase
- In general:
  - Explainable Agent Actions
  - "Knowledge in the Loop"
  - Fixpoint Iteration for new Strategies





#### Any Questions?

#### Feel free to send a mail to

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for any later questions, further regards or scenario ideas.





[1] Eric Veith, Arlena Wellßow, and Mathias Uslar. 2023. Learning New Attack Vectors from Misuse Cases with Deep Reinforcement Learning. Frontiersin Energy Research 11 (2023), 157.



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